

TREATMENT OF UNIT NON-RESPONSE IN TWO-STAGE SAMPLING WITH PARTIAL REPLACEMENT OF UNITS

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1. INTRODUCTION

Many authors have worked on sampling on successive occasions; among them are Jessen (1942), Singh (1968), Kathuria, *et al.* (1971), Okafor (1988) to mention but a few. All of the above researchers assumed total response from all the sample units on all the occasions. Singh, *et al.* (1974) using Bartholomew (1961) method of treating unit non-response proposed an estimator of the population mean for sampling on two successive occasions. Okafor and Lee (2000) applied Hansen and Hurwitz (1946) technique for treating unit non-response to double sampling for ratio and regression estimation. Okafor (2001) discussed the treatment of unit non-response in successive sampling over two occasions for element sampling.

In this paper we have attempted the extension of the treatment of unit non-response to two-stage sampling with partial replacement of units at the second stage using Hansen and Hurwitz (1946) technique. We have proposed three different estimators for the population total when sampling with partial replacement of units and with equal probability sampling at both stages. These estimators have been compared empirically using actual data from a survey on arable farming conducted by the Ministry of Agriculture, Botswana.

2. SAMPLING SCHEME

First Occasion:

Select n first stage units (fsu's) from the population of N fsu's by simple random sampling (srs). Within the i^{th} selected fsu, select a sample of m_i second stage units (ssu's) from the population of M_i ssu's again by srs. Information on the study variable y is sought from the sample ssu's. Suppose m_{1i} units respond at the first attempt and m_{2i} of the m_i ssu's not respond. Let a simple random subsample of s_{1i} ($= k_i m_{2i}$; $0 < k_i \leq 1$) units from the m_{2i} ssu's be revisited. We shall assume that all the s_{1i} ssu's gave information on y at this second attempt.

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Second Occasion:

All the n fsu's selected at the first occasion are retained for use at the second occasion. Select by srs λm_i ($0 < \lambda < 1$) ssu's from the m_i ssu's already selected at the first occasion. Suppose m'_{1i} ssu's out of the λm_i ssu's respond at the first attempt and m'_{2i} fail to respond. Let a simple random subsample of s'_{1i} ($= k_i m'_{2i}$) units be revisited. We again assume a complete response of all the s'_{1i} units at this second attempt.

In the i^{th} sample fsu, select a fresh sample of μm_i ($\lambda + \mu = 1$) ssu's from M_i ssu's by srs. For these fresh μm_i units, let u_{1i} ssu's respond and u_{2i} fail to supply the required information on the study variable. A simple random subsample of size s_{2i} ($= k_i u_{2i}$) from u_{2i} ssu's is revisited. A complete response is again assumed this time around.

3. ESTIMATION OF THE POPULATION TOTAL

For simplicity, we make the following assumptions:
 λm_i matched ssu's at the second occasion form a subset of the first occasion, $m_{1i} + s_{1i}$, responding units.

Sampling is from infinite population at both stages. M_i and the population variability remain constant at both occasions.

3.1. Notations

Let x (y) be the values of the study variate at the first (second) occasion.

$\bar{x}_{m_i}^* = (m_{1i} \bar{x}_{1i} + m_{2i} \bar{x}_{s_{1i}}) / m_i$ is the first occasion mean of the i^{th} fsu adjusted for non-response based on m_i ssu's.

\bar{x}_{1i} is the first occasion sample mean of the i^{th} fsu based on the m_{1i} ssu's.

$\bar{x}_{s_{1i}}$ is the first occasion sample mean of the i^{th} fsu based on the s_{1i} responding unit at the second attempt.

$\bar{z}_i^* = (m'_{1i} \bar{z}'_{1i} + m'_{2i} \bar{z}'_{s'_{1i}}) / \lambda m_i$; ($z = x, y$) is the sample mean adjusted for non-response based on the matched sample of ssu's.

\bar{z}'_{1i} is the sample mean for the matched sample of ssu's based on the m'_{1i} respondents at the first attempt.

$\bar{z}'_{s'_{1i}}$ is the sample mean for the matched sample of ssu's in the i^{th} fsu based on the s'_{1i} respondents at the second attempt

$\bar{y}_{u_i}^* = (u_{1i} \bar{y}''_{1i} + u_{2i} \bar{y}''_{s_{2i}}) / \mu m_i$ is the second occasion sample mean for the unmatched sample ssu's of the i^{th} fsu adjusted for non-response.

\bar{y}_{1i}'' is the second occasion sample mean for the unmatched sample ssu's in the i^{th} fsu based on the u_{1i} respondents at the first attempt.

$\bar{y}_{s_{2i}}''$ is the second occasion sample mean for the unmatched sample ssu's in the i^{th} fsu based on the s_{2i} respondents at the second attempt.

3.2. Estimators of the population total

Let us consider the first estimator of the form:

$$T_1 = \frac{N}{n} \sum_{i=1}^n M_i [\theta_i \{ \bar{y}_i^* - \beta_i^* (\bar{x}_i^* - \bar{x}_{m_i}^*) \} + (1 - \theta_i) \bar{y}_{u_i}^*] \quad (3.1)$$

β_i^* is a known constant of proportionality in the i^{th} fsu

θ_i is the weight, in the i^{th} fsu, chosen so as to make the variance of T_1 a minimum. The estimator T_1 is unbiased (see appendix for proof).

In (3.1) the first term inside the square brackets and enclosed in gothic brackets is a double sampling regression estimator, since the first occasion observation, x is used as an auxiliary variable to improve the current estimate of the population mean in each fsu. This regression estimator is suitably weighted with the basic estimator, $\bar{y}_{u_i}^*$ obtained by using the fresh sample selected on the second occasion to form one estimator of the population mean within each fsu. The same procedure is adopted in obtaining the other remaining two estimators.

It may be cumbersome to compute the weight θ_i , especially when the number of sample fsu is large. Therefore, it may be advisable to have a common weight for all the fsu's. Hence the estimator

$$T_2 = \theta \frac{N}{n} \sum_{i=1}^n M_i \{ \bar{y}_i^* - \beta_i^* (\bar{x}_i^* - \bar{x}_{m_i}^*) \} + (1 - \theta) \frac{N}{n} \sum_{i=1}^n M_i \bar{y}_{u_i}^* \quad (3.2)$$

A third estimator of the population total is obtained by using a common weight and a common regression coefficient, β_c . This estimator is of the form

$$T_3 = \phi \frac{N}{n} \sum_{i=1}^n M_i [\bar{y}_i^* - \beta_c (\bar{x}_i^* - \bar{x}_{m_i}^*)] + (1 - \phi) \frac{N}{n} \sum_{i=1}^n M_i \bar{y}_{u_i}^* = \phi T_m + (1 - \phi) T_u \quad (3.3)$$

3.3. Variance of the proposed estimators

To derive the variance of T_1 , we adopt the conditional approach and follow the procedure used in Hansen and Hurwitz (1946) estimator. The derivation of the variance is given in the appendix.

$$V(T_1) = \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N M_i^2 \left[\left\{ \theta_i^2 \frac{(1 - \mu \rho_i^2)}{\lambda m_i} + \frac{(1 - \theta_i)^2}{\mu m_i} \right\} S_i^2 + V_{2i} \left\{ \frac{\theta_i^2 (1 + \beta_i^{*2} - 2\beta_i^* \rho_{2i})}{\lambda m_i} \right\} + \frac{(1 - \theta_i)^2}{\mu m_i} \right] \quad (3.4)$$

where,

$$V_{2i} = W_{2i} (1 - k_i) S_{2i}^2 / k_i$$

S_b^2 is the population variability between the fsu's.

S_i^2 is the population variability within the i^{th} fsu.

S_{2i}^2 is the population variability of the non-respondents within the i^{th} fsu.

ρ_i is the population correlation coefficient between the first and second occasions for the i^{th} fsu.

ρ_{2i} is the within fsu population correlation coefficient between the first and second occasions for the non-respondents.

W_{2i} is the population proportion of the non-respondents.

By differentiating $V(T_1)$ with respect to θ_i and solving the derivative, we have the optimum value of θ_i as

$$\theta_{0i} = \lambda V_i / [(1 - \mu^2 \rho_i^2) S_i^2 + V_{2i} \{1 + \mu(\beta_i^{*2} - 2\beta_i^* \rho_{2i})\}] \quad (3.5)$$

$$V_i = S_i^2 + V_{2i}$$

Substituting θ_{0i} in (3.5) and simplifying, the minimum value of $V(T_1)$ becomes

$$V_0(T_1) = \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\mu m_i} (1 - \theta_{0i}) V_i \quad (3.6)$$

The optimum value of β_i^* is $\beta_{0i}^* = (\rho_i S_i^2 + \rho_{2i} V_{2i}) / V_i$

We shall use the same procedure for obtaining the variance and the optimum weight for the estimator, T_1 to derive the variance of T_2 and its optimum weight.

Hence the optimum value of θ is

$$\theta_0 = \lambda \sum_{i=1}^N \frac{M_i^2}{m_i} V_i / \sum_{i=1}^N \frac{M_i^2}{m_i} [S_i^2 (1 - \mu^2 \rho_i^2) + V_{2i} \{1 + \mu(\beta_i^{*2} - 2\beta_i^* \rho_{2i})\}]$$

While the minimum variance of T_2 is

$$V_0(T_2) = \frac{N^2}{n} S_b^2 + (1 - \theta_0) \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\mu m_i} V_i \quad (3.7)$$

Finally by minimizing the variance of T_3 with respect to ϕ , the optimum value of ϕ is

$$\phi_o = \{V(T_u) - Cov(T_m, T_u)\} / \{V(T_m) + V(T_u) - 2Cov(T_m, T_u)\} \quad (3.8)$$

While the minimum variance is

$$V_o(T_3) = \{V(T_u)V(T_m) - Cov^2(T_m, T_u)\} / \{V(T_m) + V(T_u) - 2Cov(T_m, T_u)\} \quad (3.9)$$

Where,

$$Cov(T_m, T_u) = \frac{N^2}{n} S_b^2; \quad V(T_u) = \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\mu m_i} V_i \quad (3.10)$$

$$\begin{aligned} V(T_m) = & \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\lambda m_i} V_i + \beta_c^2 \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\lambda m_i} \{\mu S_i^2 + V_{2i}\} \\ & - 2\beta_c \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{\lambda m_i} \{\mu \rho_i S_i^2 + \rho_{2i} V_{2i}\} \end{aligned} \quad (3.11)$$

The optimum value of β_c obtained by minimizing the variance of T_m , $V(T_m)$ is

$$\beta_c = \left[\sum_{i=1}^N \frac{M_i^2}{m_i} \{\mu \rho_i S_i^2 + \rho_{2i} V_{2i}\} \right] / \left[\sum_{i=1}^N \frac{M_i^2}{m_i} \{\mu S_i^2 + V_{2i}\} \right]$$

4. COMPARISON OF THE ESTIMATORS

4.1. Theoretical comparison

To gain insight into the performance of the proposed estimators and for simplicity, we shall compare only the estimator T_2 with the estimator, T_0 obtained when there is no partial matching of units.

$$T_0 = \frac{N}{n} \sum_{i=1}^n M_i \bar{y}_{m_i}^* \quad (4.1)$$

with variance

$$V(T_0) = \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N \frac{M_i^2}{m_i} V_i \quad (4.2)$$

For the purpose of comparison, we shall make the following assumptions:

$k_i = k, W_{2i} = W_2; \beta_i^* = \rho_i = \rho$ and $\rho_{2i} = \rho$ for all first stage units.

Based on these assumptions

$$V(T_0) = \frac{N^2}{n} \left[S_b^2 + S_w^2 + \frac{W_2(1-k)}{k} S_{2w}^2 \right] \tag{4.3}$$

$$S_w^2 = \frac{1}{N} \sum_{i=1}^N \frac{M_i^2}{m_i} S_i^2; S_{2w}^2 = \frac{1}{N} \sum_{i=1}^N \frac{M_i^2}{m_i} S_{2i}^2$$

The efficiencies of T_2 with respect to T_0 have been calculated for different values of $\delta = S_w^2/S_b^2, \delta_2 = S_{2w}^2/S_b^2, \rho, \rho_2, k$ and W_2 . The results are presented in tables 1 and 2 below. We have to note that since variances of T_0 and T_2 involve W_2 and k , the individual variances will be high if W_2 is high or k is small. So the efficiency of T_2 with respect to T_0 is based on the given values of W_2 and k .

From tables 1 and 2, we observe that T_2 is not necessarily more efficient than T_0 when $k = 0.4$ because here the efficiency of T_2 over T_0 is less than one when $\delta_2 = 0.5$.

This may be partly due to the assumptions used in the comparison and partly due to the nature of the estimator. But in most cases there is much to be gained in using the estimator T_2 in place of T_0 . For instance under the given assumptions, there is a gain in efficiency of T_2 over T_0 when $k = 0.1$. The efficiency is higher for $W_2 = 0.7$ than for $W_2 = 0.3$. For a given value of ρ , the gain in efficiency increases for increasing value of ρ_2 . Also for a given value of ρ_2 other than 0.1, the efficiency increases for increasing value of ρ . Further more, the efficiency of T_2 over T_0 increases for increasing value of δ_2 ; but decreases for increasing value of δ .

TABLE 1
Efficiency of T_2 with respect to T_0 for $W_2 = 0.3$

δ			0.5			1.5								
ρ			0.1	0.5	0.9	0.1	0.5	0.9						
δ_2	k	ρ_2	μ		μ		μ		μ					
			0.2	0.8	0.2	0.8	0.2	0.8	0.2	0.8	0.2	0.8		
0.5	0.1	0.1	1.26	1.26	1.21	1.24	1.09	1.16	0.96	0.96	0.95	1.01	0.90	1.07
		0.5	1.29	1.25	1.37	1.23	1.31	1.19	0.98	0.94	1.03	0.92	1.04	1.04
		0.9	1.33	1.25	1.62	1.21	1.82	1.33	1.00	0.92	1.16	0.77	1.31	0.92
	0.4	0.1	0.80	0.79	0.80	0.85	0.81	0.97	0.36	0.36	0.37	0.42	0.41	0.67
		0.5	0.80	0.78	0.82	0.77	0.85	0.91	0.36	0.34	0.37	0.34	0.40	0.54
		0.9	0.80	0.76	0.85	0.63	0.91	0.73	0.35	0.32	0.36	0.23	0.39	0.29
1.5	0.1	0.1	1.57	1.56	1.46	1.48	1.22	1.26	1.37	1.36	1.29	1.34	1.12	1.22
		0.5	1.64	1.57	1.80	1.53	1.64	1.34	1.42	1.36	1.54	1.32	1.45	1.26
		0.9	1.71	1.58	2.49	1.68	3.07	1.83	1.47	1.35	2.02	1.29	2.44	1.49
	0.4	0.1	1.08	1.07	1.05	1.09	0.99	1.09	0.71	0.70	0.71	0.78	0.72	0.95
		0.5	1.09	1.06	1.14	1.05	1.13	1.09	0.71	0.68	0.74	0.67	0.77	0.86
		0.9	1.11	1.05	1.27	0.96	1.38	1.08	0.72	0.66	0.78	0.51	0.86	0.63

TABLE 2
Efficiency of T_2 with respect to T_o for $W_2 = 0.7$

δ			0.5			1.5								
ρ			0.1		0.5		0.9		0.1		0.5		0.9	
δ_2	k	ρ_2	μ	μ	μ	μ	μ	μ	μ	μ	μ	μ	μ	μ
			0.2	0.8	0.2	0.8	0.2	0.8	0.2	0.8	0.2	0.8	0.2	0.8
0.5	0.1	0.1	1.50	1.49	1.40	1.43	1.19	1.24	1.28	1.27	1.22	1.27	1.07	1.19
		0.5	1.56	1.50	1.70	1.46	1.57	1.30	1.32	1.26	1.43	1.24	1.36	1.22
		0.9	1.62	1.50	2.26	1.57	2.71	1.71	1.36	1.25	1.79	1.17	2.12	1.35
	0.4	0.1	1.01	1.01	1.00	1.04	0.95	1.06	0.62	0.62	0.63	0.69	0.65	0.89
		0.5	1.03	1.00	1.07	0.99	1.06	1.05	0.62	0.59	0.64	0.58	0.68	0.79
		0.9	1.04	0.98	1.16	0.88	1.25	1.00	0.62	0.57	0.66	0.43	0.72	0.54
1.5	0.1	0.1	1.77	1.75	1.60	1.62	1.29	1.31	1.64	1.63	1.50	1.53	1.23	1.29
		0.5	1.86	1.77	2.10	1.72	1.85	1.42	1.72	1.63	1.92	1.59	1.73	1.37
		0.9	1.97	1.80	3.32	2.02	4.54	2.20	1.81	1.64	2.87	1.73	3.80	1.94
	0.4	0.1	1.30	1.30	1.25	1.27	1.11	1.17	1.02	1.02	1.00	1.06	0.93	1.10
		0.5	1.34	1.30	1.43	1.27	1.36	1.21	1.04	1.00	1.10	0.98	1.10	1.08
		0.9	1.38	1.29	1.73	1.27	1.96	1.40	1.06	0.98	1.26	0.84	1.43	0.99

We have to be extremely cautious in interpreting these efficiencies since the fact that the efficiency is higher for $k=0.1$ or $W_2=0.7$ does not mean that the estimate obtained from the estimator T_2 when k is small is more precise than the one obtained when k is large, as seen from table 5. The reason for this increase in efficiency is that the rate of increase of the variance of T_2 is lower than the rate of increase of the variance of T_o as k or W_2 changes.

4.2. Empirical comparison

The data used for the empirical comparison are from a survey conducted in 2000 on arable farming in Botswana. The original design was a stratified two-stage design. The strata consisted of geographical districts. In each district a sample of agricultural extension areas (land area covered by an extension worker) was selected. Within each selected extension area, a sample of farmers from the list of registered farmers in the area was selected. Information was then collected on hectares of land owned and land planted in 1999/2000 agricultural season and past four seasons from the selected farmers. Information on other variables of interest was also obtained from the farmers.

For the purpose of our empirical comparison, we have used the sample data from only five districts (Ngwaketse West, South, Central and North and Barolong) as our population data. First occasion is the 1998/1999 planting season; while the second occasion is the 1999/2000 planting season. We shall use the districts as our first stage units and farmers within districts as the second stage units. Using these data we calculated the population parameters presented in tables 3 and 4 below. We have hypothetically defined our non-respondent categories using the sample data as follows: In Ngwaketse West and Central districts, we assumed that the non-respondent stratum is made up of those farmers owning land of more than or equal to 16 hectares; in Ngwaketse South, it is those having more than or equal to 14 hectares of land. Non-respondent stratum in Ngwaketse North and Barolong districts consist of those farmers with land equal to or more than 10 and 12 hectares respectively. The large non-respondent variances shown

in table 4 is due to the fact that there is very wide disparity in the size of land owned by this category of units according to our categorizing procedure.

TABLE 3
Population parameters (overall) for 1999/2000

<i>District</i>	<i>Total (Y)</i>	M_i	S_i^2	β	ρ
Ngwaketse West	281.0002	56	26.9434	0.621	0.669
Ngwaketse South	167.6194	36	40.0094	0.536	0.429
Ngwaketse Central	253.5008	28	68.5981	0.744	0.884
Ngwaketse North	99.9994	27	15.9648	1.422	0.743
Barolong	400.6005	37	1222.8939	1.083	0.961

TABLE 4
Population parameters (non-respondents) for 1999/2000

<i>District</i>	<i>Response Category</i>	W_2	S_i^2	ρ
Ngwaketse West	Respondent		5.8144	0.422
	Non-respondent	0.43	37.5867	0.648
Ngwaketse South	Respondent		7.9163	-0.042
	Non-respondent	0.36	48.0831	0.288
Ngwaketse Central	Respondent		5.3389	0.035
	Non-respondent	0.50	83.6914	0.880
Ngwaketse North	Respondent		1.5638	0.190
	Non-respondent	0.44	22.6119	0.789
Barolong	Respondent		12.8092	0.539
	Non-respondent	0.19	1165.2324	0.924

$S_b^2 = 13123.362$; S_i^2 is the population variability within each district.

We have chosen within fsu sampling fraction of 0.1 for the purpose of computing the sampling variances of the proposed estimators.

The variances of the proposed estimators for a matching fraction of $\lambda = 0.6$ are presented in table 5 below. We observe that the estimator T_1 is the best among all the other estimators. This estimator is obtained by using individual within fsu weights and regression coefficients.

TABLE 5
Variances of the proposed estimators

<i>Estimators</i>	$k=0.2$		$k=0.8$	
	<i>Variance</i>	<i>Efficiency</i>	<i>Variance</i>	<i>Efficiency</i>
T_0	1.05490×10^6	1.000	9.98329×10^5	1.000
T_1	8.02867×10^5	1.314	7.63119×10^5	1.308
T_2	8.03857×10^5	1.312	7.64353×10^5	1.306
T_3	8.10901×10^5	1.301	7.68318×10^5	1.299

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APPENDIX

The estimator T_1 is unbiased.

Proof

$$E(T_1) = E_1 E_2 E_2' E_{s_2} (T_1) \quad (A.1)$$

E_1 = expectation over the first stage sample.

E_2 = conditional expectation over the second stage sample given the first stage.

E_2' = conditional expectation over matched sample in the i^{th} fsu.

E_{s_2} = conditional expectation over the subsample of the second stage non-respondents in the i^{th} fsu.

Taking expectations one by one

$$E_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^n M_i [\theta_i \{ \bar{y}'_i - \beta_i^* (\bar{x}'_i - \bar{x}_i) \} + (1 - \theta_i) \bar{y}_{u_i}] \quad (A.2)$$

where,

$$\bar{x}'_i = \frac{1}{\lambda m_i} \sum_{j=1}^{\lambda} x_{ij}, \quad \bar{x}_i = \frac{1}{m_i} \sum_{j=1}^{m_i} x_{ij}; \quad x = x, y \text{ and } \bar{y}_{u_i} = \frac{1}{\mu m_i} \sum_{j=1}^{\mu} y_{ij}$$

$$E_2' E_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^n M_i [\theta_i \bar{y}_i + (1 - \theta_i) \bar{y}_{u_i}] \quad (A.3)$$

$$E_2 E_2' E_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^n M_i \bar{Y}_i \quad (A.4)$$

Finally,

$$E_1 E_2 E_2' E_{s_2} (T_1) = \sum_{i=1}^N Y_i = Y$$

This completes the proof.

The unbiasedness of other estimators is proved in a similar fashion.

Proof of variance of T_1

Proof

$$V(T_1) = V_1 E_2 E_2' E_{s_2} (T_1) + E_1 V_2 E_2' E_{s_2} (T_1) + E_1 E_2 V_2' E_{s_2} (T_1) + E_1 E_2 E_2' V_{s_2} (T_1)$$

V_1, V_2, V_2' and V_{s_2} are variances analogous to the expectations defined earlier.

From (A.4)

$$V_1 E_2 E_2' E_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^n Y_i = \frac{N^2}{n} \sum_{i=1}^N (Y_i - \bar{Y})^2 / (N-1) = \frac{N^2}{n} S_b^2 \quad (\text{A.5})$$

From (A.3)

$$\begin{aligned} E_1 V_2 E_2' E_{s_2} (T_1) &= E_1 V_2 \left[\frac{N}{n} \sum_{i=1}^n M_i [\theta_i \bar{y}_i + (1-\theta_i) \bar{y}_{u_i}] \right] \\ &= \frac{N}{n} \sum_{i=1}^N M_i^2 \left\{ \theta_i^2 \frac{S_i^2}{m_i} + (1-\theta_i)^2 \frac{S_i^2}{\mu m_i} \right\} \end{aligned} \quad (\text{A.6})$$

From (A.2)

$$E_1 E_2 V_2' E_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^N M_i^2 \theta_i^2 \left\{ \frac{\mu}{\lambda m_i} S_i^2 (1-\rho_i^2) \right\} \quad (\text{A.7})$$

Further more,

$$E_1 E_2 E_2' V_{s_2} (T_1) = \frac{N}{n} \sum_{i=1}^N M_i^2 V_{2i} \left[\frac{(1-\theta_i)^2}{\mu m_i} + \frac{\theta_i^2}{\lambda m_i} (1 + \beta_i^{*2} - 2\beta_i^* \rho_{2i}) \right] \quad (\text{A.8})$$

Now combining (A.5), (A.6), (A.7) and (A.8) the variance of T_1 is

$$\begin{aligned} V(T_1) &= \frac{N^2}{n} S_b^2 + \frac{N}{n} \sum_{i=1}^N M_i^2 \left[\left\{ \theta_i^2 \frac{(1-\mu\rho_i^2)}{\lambda m_i} + \frac{(1-\theta_i)^2}{\mu m_i} \right\} S_i^2 \right. \\ &\quad \left. + V_{2i} \left\{ \frac{\theta_i^2 (1 + \beta_i^{*2} - 2\beta_i^* \rho_{2i})}{\lambda m_i} + \frac{(1-\theta_i)^2}{\mu m_i} \right\} \right] \end{aligned} \quad (\text{A.9})$$

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RIASSUNTO

Trattamento delle mancate risposte totali nel campionamento a due stadi con sostituzione parziale delle unità

Vengono presentati tre stimatori per il totale di popolazione basati su un disegno campionario a due stadi con sostituzione parziale solo delle unità del secondo stadio. Gli stimatori proposti sono costruiti tenendo conto dell'ipotesi di presenza di mancata risposta totale, e l'aggiustamento per la mancata risposta è basato sulla tecnica proposta da Hansen e Hurwitz (1946). Da un'analisi empirica emerge che gli stimatori per il totale di popolazione che usano pesi individuali per le unità di primo stadio hanno migliori prestazioni degli stimatori che usano pesi comuni. Sul versante teorico viene dimostrato che maggiore è il rapporto fra la variabilità entro le unità di primo stadio relative ai non rispondenti e la variabilità fra le unità di primo stadio, maggiore è il guadagno che si ottiene, in termini di efficienza, usando gli stimatori proposti invece degli stimatori che si ottengono quando non c'è *matching* parziale delle unità.

SUMMARY

Treatment of unit non-response in two-stage sampling with partial replacement of units

Three separate estimators, for the estimation of the population total, based on two-stage sampling design on two successive occasions with partial replacement of secondary stage units only have been presented. For these estimators it is assumed that there is unit non-response. Hence, Hansen and Hurwitz (1946) technique has been used to adjust for the non-response. Empirically, it has been found that the estimator that uses individual weights within first stage units perform better than the other estimators that use common weights in estimating the population total. Theoretically, it has also been shown that the larger the ratio of the within first stage unit variability of the non-respondents to the between first stage unit variability the higher the gain in efficiency of the proposed estimators over the estimator obtained when there is no partial matching of units.