

## THE AUTOREGRESSIVE METRIC FOR COMPARING TIME SERIES MODELS<sup>1</sup>

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### 1. INTRODUCTION

In the last decades, many factors stimulated an increasing interest towards dissimilarity measures for comparing time series data; in particular:

- thousands of financial, hydrological, meteorological, environmental, seismic, astronomical time series are regularly collected and their analysis demands for fast and effective methods for clustering and discriminating in order to select representative elements of homogenous groups of series;
- time series data mining is a research area where effective selection criteria are needed as long as a vast amount of information is now available on web and data warehouse;
- computers speed and numerical algorithms efficiency allow to monitor variability of dynamic phenomena in real time;
- complexity of systems may be investigated only by checking several individual time behavioural (as in Medicine, Control and Safety area, for instance) and departure from standard condition is a relevant objective for regular monitoring.

In this respect, statistical literature includes a number of proposals in order to solve such problems. Given that the methodological issue concerns the concept of dissimilarity among time series, such ideas generated different measures mainly aimed at solving the peculiar problem at hand. The main difference relies among proposals concerning the processes which generate data, the class of models chosen for parsimonious representations of dynamic phenomena and the time series realizations, respectively.

In the following, we will quote some of them but we prefer to focus on a specific solution whose generality and pervasiveness we will confirm throughout this

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work. Thus, we deepen the foundations of the Autoregressive (AR) metric as a simple and effective measure of dissimilarity among time series in order to spread current researches and to suggest new developments. Extensive reviews on clustering and discrimination of time series have been pursued by Maharaj (2000), Liao (2005), Corduas (2003, 2007), Piccolo (2007), Corduas and Piccolo (2008).

The paper is organized as follows: after a review of motivations and genesis of the AR metric, the rationale of the proposal, its statistical and topological properties are discussed in sections 3-4. Section 5 is devoted to inferential issues mainly based on the asymptotic distribution of the maximum likelihood estimator of the distance. Extensions and generalizations are presented in section 6 whereas a synthetic analysis of relevant alternatives is discussed in section 7. Some concluding remarks end the paper.

## 2. MOTIVATIONS AND DEVELOPMENT OF THE AR METRIC

The public domain release of the AR metric – as a distance measure among time series generated by ARIMA models – begins on 14 September, 1983, during my visit at the Department of Statistics, University of Wisconsin, Madison (USA), when I was invited by prof. George Box to give a Seminar on “*A Distance Measure among ARIMA Models?*”.

Indeed, I experienced this problem in a previous research involving the construction of an ARIMA model for the monthly wholesale prices index  $P_t$  in Italy (Piccolo, 1972). In this circumstance, I compared two models for  $P_t$ :

$$\text{Model 1: } (1 - 1.30B + 0.40B^2) \nabla \log(P_t) = (1 - 0.12B)a_t$$

$$\text{Model 2: } (1 - 0.45B) \nabla^2 \log(P_t) = (1 - 0.45B + 0.05B^2)b_t$$

by plotting the Autoregressive coefficients ( $\pi_j$ ) obtained from the ARIMA operators, as reported in Figure 1. In that occasion, I was comparing an ARMA(2,1) model for the inflation rate with an ARMA(1,2) model for the *acceleration rate*  $\nabla^2 \log(P_t)$  of the wholesale prices. It is evident that when comparing linear models fitted to the same data set the visual inspection of the original coefficient is not conclusive. On the contrary, the Autoregressive approximation enhances the strong similarity between the estimated models.

As a benchmark, we compare the following three ARMA ( $p, q$ ) models of increasing complexity and characterized by the parameters:

TABLE 1  
*ARMA ( $p, q$ ) models of increasing complexity*

| Models                     | $\phi_1$ | $\phi_2$ | $\phi_3$ | $\phi_4$ | $\theta_1$ | $\theta_2$ | $\theta_3$ |
|----------------------------|----------|----------|----------|----------|------------|------------|------------|
| M <sub>1</sub> : ARMA(2,1) | 0.81     | -0.62    | –        | –        | 0.12       | –          | –          |
| M <sub>2</sub> : ARMA(3,2) | 1.33     | -1.04    | 0.32     | –        | 0.57       | -0.05      | –          |
| M <sub>3</sub> : ARMA(4,3) | 0.48     | 0.09     | -0.56    | 0.27     | -0.21      | 0.39       | -0.04      |

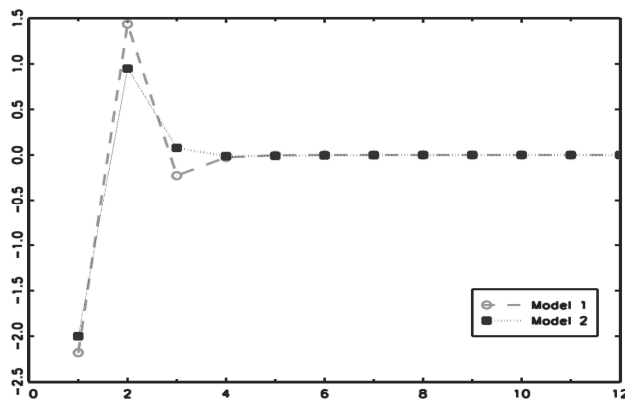


Figure 1 – Autoregressive coefficients obtained by two models for the same series.

The question is: *How different are these different ARMA models?* A simple way to face the problem could be via a parametric approach, by comparing the parameter vectors of common length:

$$\begin{aligned}
 M_1 \rightarrow \beta_1 &= (0.81, -0.62, 0, 0, 0.12, 0, 0)' ; \\
 M_2 \rightarrow \beta_2 &= (1.33, -1.04, 0.32, 0, 0.57, -0.05, 0)' ; \\
 M_3 \rightarrow \beta_3 &= (0.48, 0.09, -0.56, 0.27, -0.21, 0.39, -0.04)' ,
 \end{aligned}$$

by means of a Euclidean metric defined by:

$$\delta(M_i, M_j) = \sqrt{(\beta_i - \beta_j)'(\beta_i - \beta_j)} \tag{1}$$

This coefficient-based criterion leads to the following results:

$$\delta(M_1, M_2) = 0.868; \quad \delta(M_1, M_3) = 1.123; \quad \delta(M_2, M_3) = 1.911.$$

Thus, one reaches the *wrong* conclusion of a large dissimilarity among the models. Instead, all the *models are almost coincident* since they were obtained by using the rational operators:

$$\psi_1(B) = \frac{1 - 0.12B}{1 - 0.81B + 0.62B^2}; \quad \psi_2(B) = \psi_1(B) \frac{1 - 0.45B}{1 - 0.52B}; \quad \psi_3(B) = \psi_2(B) \frac{1 + 0.78B}{1 + 0.85B}$$

Their similarity can be recognized by looking for the roots of polynomial operators in the complex plane, or simply by comparing their spectra as shown in Figure 2. This situation is common when we get different parametric formulations by means of some automatic fitting criterion.

Anyway, notice that spectra cannot be computed for non-stationary data and thus the previous visual aids fail if we need to compare ARIMA  $(p, d, q)$  models with different orders of difference operator.

Previous evidence discourages from considering to compare parameters of ARIMA models in their rational formulation as the basis for introducing a distance measure since this criterion is not resistant with respect to near-cancellation of ARMA operators.

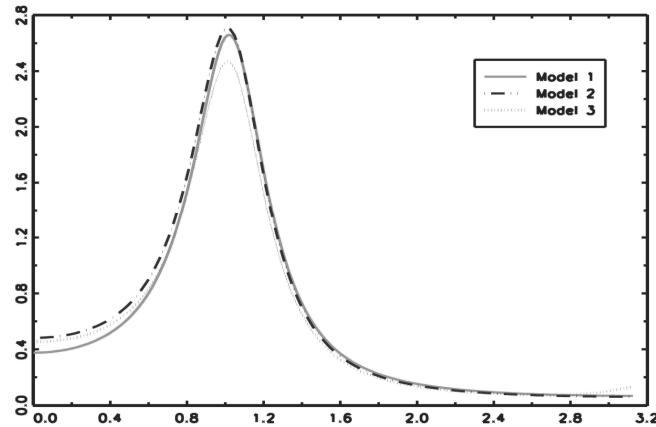


Figure 2 – Operators in the spectral domain of three ARMA models.

The genuine idea for a metric came out as the answer to a methodological issue raised during the *DESEC* project (1982-85), a national research aimed at convincing the Italian public Institutions to adopt a shared and unique seasonal adjustment procedure.

Given the need for the implementation of a massive seasonal adjustment experiment with thousands of time series, I faced the following problem: “How to choose few *representative series* from a large data set in order to reduce time and costs of the statistical analysis?” Formally, the problem is:

“Given a collection of time series  $X_{j,t} \in C$ , select a series  $X_t^*$  such that:

$$\text{distance}(X_{j,t}, X_t^*) = \min! \quad \forall X_{j,t} \in C. \quad (2)$$

Since the series to be considered were generated from different areas with different time lengths, the investigation required the introduction of a completely general metric. These considerations were firstly diffused among a subset of Italian researchers by means of the *DESEC* research Technical Reports series, as “*A Distance Measure for ARIMA Models*” (RS 21/1984).

The journal “*Statistica*” published the first paper on the new proposed metric (Piccolo, 1984a) and the distribution of the maximum likelihood (ML) estimator of the metric for pure AR processes was presented at the ASA Conference in Washington (Piccolo, 1989). Then, after a long revision process, a contribution on this topic (submitted in 1986) appeared in “*Journal of Time Series Analysis*” (Piccolo, 1990) and this paper became the standard international reference for the AR metric.

It is worth considering that other criteria are based on AR coefficients. In speech recognition analyses, the AR coefficients denoted as LPC (=Linear Predictor Coding) were used in order to synthesize the voice signals for a specific word (Gray and Markel, 1976); however, the method was finalized *only* to fitting and testing purposes as in Basawa *et al.* (1984). In this respect, De Souza (1977) and Thomson and De Souza (1985) introduced the Mahalanobis distance between AR models and derived its distributional properties. Many recent medical applications in ECGs and EEGs classifications still refer to this kind of approach (Kos̆c, 2000; Ge *et al.*, 2002).

For many years, the AR metric has been used in several fields (with some original emphasis on seasonal adjustment procedures, as reported by Agustin Maravall, Spain and David Findley, Usa) and many statistical papers have been published. From the methodological point of view, a significant advancement on these topics has been achieved thanks to Corduas (1996, 2000a) who assessed distributional properties of the AR metric in a general setting, as we will discuss in section 5.

### 3. STATISTICAL FOUNDATIONS

Dictionaries define *distance* as: “the property created by the space between two objects or points; the size of the gap between two places; the interval between two times;...”

Instead, *metric* is: “a system of related measures that facilitates the quantification of some particular characteristic; a function of a topological space that gives, for any two points in the space, a value equal to the distance between them,...”

Then, a preliminary remark applies: distance is a *concept* that may be transformed into an operational tool by means of some conventional *measure*. It is correct to argue in favor or against a specific metric, since a metric is strictly determined by the purpose of a research: *different metrics are acceptable if different objectives are pursued.*

In fact, when *objects* to be compared are *time series*, an effective metric should satisfy the following requirements:

- it is simple to compute and provides meaningful interpretation of data;
- it is dependent on the stochastic structure of the data generating process;
- it is implemented for the largest class of stochastic processes generally consistent with observed time series;
- it is not dependent both on the length of data and the unit of measurement of time series;
- it is robust with respect to local anomalies in the series to be compared.

In addition, our approach relies on the fundamental paradigm which relates a *time series* to the generating *stochastic process* via a *statistical model*. As a consequence, we will define the metric on a well defined space of stochastic processes which is adequate to generate almost any real time series. The statistical determination of the features of such processes may be effectively recovered on the basis of the

observed realizations by means of inferential procedures, which are consistent and asymptotically efficient.

From a statistical point of view, the AR metric is justified by a fundamental theorem which we quote from Brockwell and Davis (1991, 130-133): “for *any* stationary process with a continuous spectrum  $f(\omega)$  there exists a finite order AR ( $p$ ) whose spectrum  $f_{AR}(\omega)$  is as close as possible in absolute value to  $f(\omega)$  uniformly on  $[-\pi, \pi]$ ”.

The theorem is extended to moving average (MA) processes and, for numerical efficiency, to mixed ARMA structures. As a consequence, the AR operator provides the simplest and effective approximation of any stationary process or any process that may be transformed to stationarity. In fact, the theorem applies to both linear and not linear processes.

Specifically, given the process  $X_t$ , we consider ARIMA models for  $Z_t = g(X_t) - f_t$ , where  $Z_t$  is obtained after  $g$ -transforming  $X_t$  (in order to reduce asymmetries, improve Gaussianity and take into account of non-linearities) and after removing any deterministic components  $f_t$  (such as trading days, calendar effects, outliers and mathematical functions of time, including constants).

Hereafter, we will refer to Box and Jenkins (1970) standard notation and we will assume that  $Z_t$  is a zero mean invertible ARIMA process defined as:

$$\varphi(B)\nabla^d\nabla_s^D Z_t = \mathcal{G}(B)a_t, \quad (3)$$

where  $a_t$  is a White Noise (WN) process with constant variance  $\sigma_a^2 < +\infty$ . If  $a_t$  is a Gaussian process, given the initial values, the operators  $\varphi(B), \mathcal{G}(B)$  and the WN variance  $\sigma_a^2$  characterize the probability distribution of the process  $Z_t$ .

The polynomials  $\varphi(B) = \phi(B)\Phi(B^s)$  and  $\mathcal{G}(B) = \theta(B)\Theta(B^s)$ , for any  $s \geq 0$ , have no common factors, and all the roots of  $\varphi(B)\mathcal{G}(B) = 0$  lie outside the unit circle. We denote by  $\mathcal{L}$  the class of invertible linear stochastic processes  $Z_t \sim ARIMA$  such that the MA operators have *all the roots outside the unit circle*.

The *invertibility* assumption ensures the absolute (and squared) convergence of the  $\pi_j$  coefficients so that  $Z_t$  can be represented in terms of its past values according to:

$$\pi(B)Z_t = a_t \Leftrightarrow Z_t = \pi_1 Z_{t-1} + \pi_2 Z_{t-2} + \dots + a_t, \quad (4)$$

where:  $\pi(B) = (1-B)^d(1-B^s)^D \varphi(B)\mathcal{G}^{-1}(B) = 1 - \sum_{j=1}^{\infty} \pi_j B^j$ .

For any  $Z_t \in \mathcal{L}$ , the *forecast function*  $F_t = \mathbb{E}\{Z_t | Z_{t-1}, Z_{t-2}, \dots\}$  is given by:

$$F_t = \pi_1 Z_{t-1} + \pi_2 Z_{t-2} + \dots, \quad (5)$$

whereas a corresponding orthogonal representation is:  $Z_t = F_t + a_t, F_t \perp a_t, \forall t$ .

Let  $X_t \in \mathcal{L}$  and  $Y_t \in \mathcal{L}$  be invertible processes whose forecast functions may be expressed via the corresponding AR coefficients:

$$\boldsymbol{\pi}_x = (\pi_{1,x}, \pi_{2,x}, \dots, \pi_{j,x}, \dots); \quad \boldsymbol{\pi}_y = (\pi_{1,y}, \pi_{2,y}, \dots, \pi_{j,y}, \dots). \quad (6)$$

Then, given the absolute convergence of the  $\pi$ -sequences in  $\mathcal{L}$ , Piccolo (1984a, 1990) introduced a metric between two ARIMA processes,  $X_t$  and  $Y_t$ , with given orders, as the Euclidean distance between the  $\pi$ -weights of their corresponding AR( $\infty$ ) formulation:

$$d(X_t, Y_t) = [(\boldsymbol{\pi}_x - \boldsymbol{\pi}_y)'(\boldsymbol{\pi}_x - \boldsymbol{\pi}_y)]^{\frac{1}{2}} = \sqrt{\sum_{j=1}^{\infty} (\pi_{j,x} - \pi_{j,y})^2}. \quad (7)$$

The most immediate and convincing interpretation of the AR metric stems from the following result: given the same set of initial values, *the distance between two ARIMA processes is zero if and only if the corresponding models produce the same forecasts.*

The distance  $d(X_t, Y_t)$  is a well defined measure of *structural dissimilarity* among any processes belonging to  $\mathcal{L}$  and its value is determined by all the components of the stochastic structures to be compared. Notice that, if both  $X_t \in \mathcal{L}$  and  $Y_t \in \mathcal{L}$ , then  $d(X_t, Y_t)$  is always well defined irrespective of the fact that one or both processes are stationary or non-stationary.

Since AR metric takes rational operators into account before their expansion into  $\pi_j$  coefficients, it may be considered fairly robust with respect to over-parameterization (although we discourage this practice in time series inference).

We mention a recurrent objection against the AR metric which assesses that it does not take the WN variance into account. Indeed, this quantity is a mere scale factor depending on the measurement unit: it is well known that, for stationary linear processes, the noise-to-series variances ratio is a function of the process parameters. To face the objection, different proposals have been introduced in the literature and we just quote two of them since they are motivated by different needs.

In order to detect influential observations, Peña (1990) considered the squared Mahalanobis AR distance to assess how the parameters of a model change when each observation is in turn removed from the time series and replaced by the estimated missing value. Such measure is not a metric; it explicitly depends on the WN variance, and it turns out that it is related to the squared Euclidean distance between the one step ahead forecast values of the series. Consequently, it is strongly affected by the scale unit.

Similar considerations apply to the proposal of Tong and Dabas (1990), which introduced *similarity* and *dissimilarity measures* for clustering the residuals obtained from various statistical models fitted to the same time series, and to Maharaj (1996, 1999, 2000) results aimed at classifying and clustering time series data.

These criteria are effective for the purposes that the Authors considered (outliers detection, clustering of several homogeneous time series, comparing residuals from different models fitted to the same series, and so on) but they cannot be used to compare time series obtained by completely different data generating processes. For instance, these proposals are not even useful to compare a model fitted to a time series with a model fitted to the logarithm of the same series.

#### 4. TOPOLOGICAL PROPERTIES

The introduction of  $d(X_t, Y_t)$  over  $\mathcal{L}$  transforms  $\mathcal{L}$  in a metric space, and any sub-class of  $\mathcal{L}$  (e.g. the *AR*, *MA*, *ARMA*, *IMA* classes) is a well defined metric space with respect to the same metric.

Any WN process is the *origin* for the metric space  $\mathcal{L}$ , and for any  $Z_t \in \mathcal{L}$ , the *norm* is defined by:  $\sum_j \pi_j^2 < +\infty$ . In addition, we are able to define the *angle*  $\alpha$  between two processes  $X_t \in \mathcal{L}$ ,  $Y_t \in \mathcal{L}$  by means of:

$$\cos(\alpha) = \sum_j \pi_{j,x} \pi_{j,y} \left( \sum_j \pi_{j,x}^2 \sum_j \pi_{j,y}^2 \right)^{-1/2}. \quad (8)$$

The metric space  $\mathcal{L}$  is *isometric* with respect to seasonal processes since, for any  $s > 0$ :

$$d(\pi_x(B)X_t, \pi_y(B)Y_t) = d(\pi_x(B^s)X_t, \pi_y(B^s)Y_t). \quad (9)$$

For multivariate applications of the metric it is important to define the distance of a single series from a given class, and the diameter of a class of time series models.

Given a series  $X_t \in \mathcal{L}$  and a class of time series models  $\mathcal{B} \subset \mathcal{L}$ , the distance of  $X_t$  from  $\mathcal{B}$  is defined by:

$$\text{dist}(X_t, \mathcal{B}) = \inf \{d(X_t, Y_t), Y_t \in \mathcal{B}\}. \quad (10)$$

For any class  $\mathcal{B} \subset \mathcal{L}$ , the *diameter* is defined by:

$$\text{diam}(\mathcal{B}) = \sup \{d(X_t, Y_t), X_t \in \mathcal{B}, Y_t \in \mathcal{B}\}. \quad (11)$$



Finally, it may be shown that the sub-class of AR processes has a *finite* diameter. Notice that the size of the diameter has an immediate impact on the reliability of a selected time series model to represent the whole set.

It is of interest to consider a prototypical example for computing the AR metric. Let  $X_t \in \mathcal{L}$  and  $Y_t \in \mathcal{L}$  two ARMA(1,1) processes. From a formal expansion of the corresponding  $\pi_j$  coefficients:

$$\pi_{j,x} = (\phi_x - \theta_x)\theta_x^{j-1}; \quad \pi_{j,y} = (\phi_y - \theta_y)\theta_y^{j-1}; \quad j = 1, 2, \dots$$

we obtain:

$$d^2(X_t, Y_t) = \frac{(\phi_x - \theta_x)^2}{1 - \theta_x^2} + \frac{(\phi_y - \theta_y)^2}{1 - \theta_y^2} - 2 \frac{(\phi_x - \theta_x)(\phi_y - \theta_y)}{1 - \theta_x \theta_y}.$$

This result is completely general for computing also the distance between processes belonging to the sub-classes AR(1), MA(1), ARIMA(0,1,0), ARIMA(0,1,1): it suffices, in the previous formula, to let some parameters equal to 0 and/or 1.

For instance, by letting  $\phi_x = \phi_y = 0$  and  $\theta_x = 1 - \lambda_x; \theta_y = 1 - \lambda_y$ , we obtain the distance between the ARIMA(0,1,1) processes implied by the so-called *exponential smoothing* procedure (EWMA processes).

By letting  $\phi_x = \phi_y = 1$ , we obtain the distance between two non-stationary MA(1) processes:

$$d^2(X, Y) = 2 \frac{(\theta_x - \theta_y)^2}{(1 + \theta_x)(1 + \theta_y)(1 - \theta_x \theta_y)}.$$

From the last expression, we get:

$$\lim_{\theta_x \rightarrow 1} d^2(X, Y) = \frac{1 - \theta_y}{1 + \theta_y}; \quad \lim_{\theta_y \rightarrow 1} d^2(X, Y) = \frac{1 - \theta_x}{1 + \theta_x}.$$

In this case, the metric is well defined also for *borderline non-invertible* ARIMA processes (Piccolo, 1990). Notice that here  $X_t$  and  $Y_t$  are cointegrated of order 1 and borderline non-invertible processes.

## 5. COMPUTATIONAL ISSUES AND STATISTICAL INFERENCE

From an operational point of view the AR metric addresses several problems related to the correct specification of time series models to be compared, efficient estimation of parameters and effective numerical computations of the AR coefficients. We defer to Corduas and Piccolo (2008) for most of them and we limit

ourselves to briefly discuss the model selection step given that specification is one of the critical and controversial point with respect to a correct use of this metric.

First of all, computations are feasible if one knows processes whereas in the real world researcher need to infer on them. Thus, if one needs to compare several ARIMA processes on the basis on their finite realizations, it is effective to obtain the estimation of the parameter vector by maximum likelihood methods which require a specification of the orders of the ARIMA models. In this respect, strategies split into *ad hoc* modelling criteria (for small/moderate size of the data set) and *automatic* modeling via AIC or BIC criteria (for large data set).

As a matter of fact, one has to choose between *ad hoc* modelling of all series or to rely on some automatic identification criterion, within a predefined class of models. In this area, some caution is necessary since most of the published works compare the AR metric with alternative measures by means of massive automatic selection criteria. In these cases, we are not convinced that comparison is really performed among metrics and not among selection criteria.

When the number of series to be analyzed may be conveniently handled, we always prefer *ad hoc* modelling procedures before using AR metric since the strength of the proposal relies on the possibility to fit the ARMA operators to real data in an efficient way: this mostly applies when some doubt concerns the use of non-stationary operators.

Afterwards, the distribution of the distance estimator is required to assess significant dissimilarities. A preliminary result, concerning the comparison of AR models based on ML estimators, was obtained by Piccolo (1989). Instead, Sarno (2000, 2001) discusses asymptotic distribution of the metric derived from least squares estimators when MA processes are involved.

The asymptotic distribution of the metric for any ARIMA processes in  $\mathcal{L}$  has been fully derived by Corduas (1996), together with efficient algorithms (Corduas, 2000a). Briefly, assuming that efficient ML methods have been implemented for estimating the  $k = p + q + P + Q$  parameters of the ARMA models to be compared, it can be shown that, under the null hypothesis  $H_0 : \boldsymbol{\pi}_x = \boldsymbol{\pi}_y$ :

$$\hat{d}^2(X_t, Y_t) \sim \sum_{j=1}^k \lambda_j \chi_{g_j}^2, \quad (12)$$

where  $\chi_{g_j}^2$  are independent Chi-square random variables, with  $g_j$  degrees of freedom given by the multiplicity of each eigenvalue (usually,  $g_j \equiv 1$ ) and  $\lambda_j$  are the eigenvalues of a convenient matrix  $\mathbf{C}_0$  of order  $(k \times k)$ .

We write the non-stationary  $\boldsymbol{\pi}$  coefficients as the linear transformation:  $\boldsymbol{\pi} = \mathbf{A}\boldsymbol{\pi}^A + \mathbf{v}$  of the stationary coefficients  $\boldsymbol{\pi}^A$ , for some non-stochastic matrix  $\mathbf{A}$  and vector  $\mathbf{v}$ . For ARIMA models, the matrix  $\mathbf{C}_0$  is defined by:

$$\mathbf{C}_0 = (n_x^{-1} + n_y^{-1})\mathbf{A}\mathbf{B}\mathbf{V}\mathbf{B}'\mathbf{A}', \quad (13)$$

where  $n_y$  and  $n_x$  are the lengths of the realizations of  $X_t$  and  $Y_t$ , respectively, and the matrices  $\mathbf{A}, \mathbf{B}, \mathbf{V}$  can be derived from the model operators by effective algorithms.

For computing critical values, standard results may be applied to this problem: specifically, we may exploit results on the approximation of a linear combination of Chi-square random variables by means of a linear transformation of a Chi-square, with convenient degrees of freedom (as proposed by Corduas, 1996), or we may apply a Box-Cox transformation to the estimator  $\hat{d}$  in order to improve its convergence to Normality (as proposed by D'Elia, 2000). An updated account of this approach for clustering purposes has been obtained by Corduas and Piccolo (2008).

Finally, as explorative tools for visualizing clusters and representations induced by the AR metrics, we quote dendrograms generated by a cluster analysis based on such distance, visual displays (Tran-Luu and DeClaris, 1997), multidimensional scaling representations (Piccolo, 1984b) and graph methods (Sarno, 2005; Palomba *et al.*, 2008).

## 6. EXTENSIONS AND GENERALIZATIONS OF THE AR METRIC

Distance is an ubiquitous concept in Statistics and it is able to meet most of the need for empirical analysis. Then, the AR metric has been applied in several scientific fields such as Economics, Finance, Demography, Medicine, Linguistic, Signal processing, Environmental Sciences, Hydrology and Meteorology, Seismology, Astronomy, and so on.

In addition to the standard comparison of time series and statistical models, the literature registers different variants of the original proposal of an AR metric:

- methodological arguments aimed at extending the proposal from a statistical point of view;
- statistical methods aimed at specific objectives;
- fields of applications and different perspectives leading to an effective usage of a metric among time series models.

### 6.1 Generalizations and methodological extensions

Firstly, the AR metric may be generalized in order to compare (long-memory) fractional difference processes  $Z_t \sim \text{ARFIMA}(p, d, q)$ , when  $|d| < 0.5$ . In this case, for the fractional difference operator  $\nabla^d = (1 - B)^d$  we get:

$$\pi_i(d) = (-1)^{i+1} \binom{d}{i}, \quad i = 1, 2, \dots; \quad \sum_{i=1}^{\infty} \pi_i^2(d) = \frac{\Gamma(1+2d)}{\Gamma^2(1+d)} - 1 < +\infty.$$

Remember that  $Z_t \in \mathcal{L}$  as long as  $d > -0.5$  and the Euclidean distance between two  $\pi$ -sequences is well defined even if one or both are generated by AR-FIMA operators. In this way, the AR metric is generalized to the class of invertible ARFIMA processes and may be correctly applied if one or both processes encompass long-memory behaviour (Corduas and Piccolo, 2006). Instead, most of the alternative proposals of the literature cannot share this remarkable property with the AR metric.

A second relevant extension of the AR metric has been proposed by Otranto (2004, 2008) for the classification of the volatility of financial time series generated by GARCH models and further developed in several directions, even multivariate (Otranto, 2009, 2010; Lisi and Otranto, 2010; Otranto and Trudda, 2008a, 2008b). The starting point is to apply the AR metric to measure the distance between squared noise processes; then, cluster algorithms are applied in order to classify the volatility of several stock prices and to study their interdependence. The joint application of the AR metric to both ARIMA and GARCH model components proves to be a sound extension of the approach since it accounts for important components often detected in the majority of real time series when we are faced with clustering and discrimination objectives in economic and financial data sets.

In the econometric arena, a significant contribution to enlarge the spectrum of applications derives from the idea that the AR metric helps in detecting the relationship between feedback in stochastic systems and thus it may be a useful tool for testing Granger causality (Triacca, 2004a). This approach has been recently generalized in a multivariate context by Di Iorio and Triacca (2011) who formally proved that for checking non-causality in the sense of Granger is sufficient to compute the AR metric among two univariate processes. Some simulation experiments and a real case study sharply favour their proposal with respect to standard econometric tests thanks to a dominant power function.

## 6.2 Further statistical developments

Corduas (2000b) exploited the AR metric as an estimation method in order to find the fractional value of  $d$  such that the process  $\nabla^d Z_t = a_{xt}$  is as close as possible to the  $X_t \sim \text{ARMA}(1,1)$  process defined by:  $(1 - \phi B)X_t = (1 - \theta B)a_{xt}$ , where the closeness is measured by the AR metric.

Then, given the estimates  $\hat{\beta} = (\hat{\phi}, \hat{\theta})'$ , the problem is to find  $d$  such that:

$$G^\circ(d) = \sum_{i=1}^{\infty} [\pi_i(d) - \pi_i(\hat{\beta})]^2 \approx \sum_{i=1}^L \left[ (-1)^i \binom{d}{i} - (\hat{\phi} - \hat{\theta})(\hat{\theta})^{i-1} \right]^2 = \min! \quad (14)$$

for some fixed  $L = 100, 150$ , say. Further aspects of the approach have been developed by Corduas and Piccolo (2001, 2003, 2006); D'Elia and Piccolo (2002a, 2002b).

A different proposal aimed at a spectral decomposition of the AR metric has been introduced by Iannario and Piccolo (2011) and their result relies on a theorem proved for computing this distance in an effective way. In fact, Corduas (1992a) showed that: *the squared AR metric is always the variance of a well defined stationary process.*

Specifically, we denote by

$$\delta_j = |\pi_{j,x} - \pi_{j,y}|, \quad j = 1, 2, \dots$$

the absolute difference of the AR expansion of processes  $X_t \in \mathcal{L}$  and  $Y_t \in \mathcal{L}$ . Then, we introduce the stationary process:

$$W_t = \eta_t + \alpha_1 \eta_{t-1} + \alpha_2 \eta_{t-2} + \dots = \alpha(B)\eta_t,$$

where  $\eta_t \sim \mathcal{WN}(0, \delta_1^2)$  and the coefficients  $\alpha_j$  are obtained as:

$$\alpha_j = \frac{\delta_{j+1}}{\delta_1}, \quad j = 1, 2, \dots$$

It is immediate to show that:

$$\text{Var}(W_t) = \sum_{j=1}^{\infty} |\pi_{j,x} - \pi_{j,y}|^2 = d^2(X, Y). \quad (15)$$

The process  $W_t$  is obtained by filtering the  $\mathcal{WN}$  process  $\eta_t$  by means of a linear operator  $\alpha(B)$  where the differences of the AR expansions of both processes  $X_t$  and  $Y_t$  are taken into account. It is evident that the time dynamics of  $W_t$  reflects characteristics of both processes to be compared. Two processes  $X_t$  and  $Y_t$  with similar behaviour produce small  $\alpha_j$  coefficients while processes with quite dissimilar structures induce large coefficients  $\alpha_j$ .

Although  $W_t$  is a fictitious process, its statistical analysis helps in investigating the structural dissimilarity among  $X_t$  and  $Y_t$  as synthesized by the AR metric. The process  $W_t$  may be non-invertible but it is *always stationary*. Thus, it admits a symmetric spectral function defined by:

$$g(\omega) = \frac{\delta_1^2}{\pi} |\alpha(e^{-i\omega})|^2, \quad 0 < \omega < \pi.$$

Then, the spectral decomposition of the AR metric immediately follows:

$$d^2(X, Y) = \text{Var}(W_t) = \int_0^\pi g(\omega) d\omega.$$

This result allows to ascertain whether some components at low, high, periodic, seasonal frequencies contribute to the determination of the value of  $d^2(X, Y)$ . In addition, since  $g(\omega)/d^2(X, Y)$  shares all the properties of a well defined density function over  $(0, \pi)$ , one should consider that a high accumulation of variance of  $W_t$  around some range of angular frequencies means that such components are important for explaining the computed distance among processes, and thus for increasing dissimilarities among them.

Finally, we remember that – for computing the AR metric as a variance – Corduas (1992b) suggested efficient numerical algorithms based on a state-space representation of the ARMA processes (Anderson and Moore, 1979) or on the autocovariance generating function of the  $W_t$  process (Tunncliffe Wilson, 1979).

Further methodological issues concerning the AR metric include the computation of power functions in time series analysis (Gonzalo and Lee, 1996); the consequences on the metric when the series are correlated (Corduas, 1992b); a test of parallelism between two ARIMA processes (Triacca, 2004b).

### 6.3 Different applications and perspectives

We limit ourselves to mention the applications we are aware of in several scientific fields and with non standard objectives:

- regional classification of streamflow time series (Corduas, 2011);
- redundancy in environmental monitoring networks (Costanzo and Sarno, 2000; Sarno, 2005);
- data mining problems (Agrawal *et al.*, 1994; Ng and Huang, 1999);
- validation of seasonal adjustment procedures (Corduas and Piccolo, 1999a, 1999b); selecting between direct and indirect model-based seasonal adjustment (Otranto and Triacca, 2002).
- representativeness of an aggregated index (Caceres *et al.*, 1993);
- convergence of inflation rates in the EU countries (Sarno and Zazzaro, 2002; Palomba *et al.*, 2008);
- plotting time series as objects in a multidimensional scaling space (Corduas, 1984; Piccolo, 1984b, 1987);
- comparison of stochastic components of a time series (Corduas and Piccolo, 1995); similarity among original series and canonical components (Quilis, 2004);
- time series clustering (Piccolo, 1984; Corduas, 1985b; Cano *et al.*, 1992; Corduas and Piccolo, 1996; Maharaj, 1996, 2000; Grimaldi, 2004; Liao, 2005) and time series discrimination (Corduas, 2004);
- classification of multivariate time series (Maharaj, 1999; Galeano and Peña, 2000);
- detecting extreme (anomalous) behaviors in a homogeneous time series data set (Corduas and Piccolo, 1999a);

## 7. DISCUSSION OF RELATED ALTERNATIVES

An accurate discussion of relative merits and pitfalls of the alternatives to the AR metric is out of the objectives of this paper. We defer to the literature for an extensive treatment of such topics and briefly review some of them since they are more related with AR metric.

We mention some metrics based on autocorrelation sequences (as those proposed by Bohte *et al.*, 1980, and Mélard and Roy, 1984) which are conceptually related to well known tests in residual time series analysis, as Box and Pierce (1970) and Ljung and Box (1978) tests, for instance. In this regard, we notice that metrics based on the comparisons of partial autocorrelation sequences are more effective in the subspace of stationary processes (given some orthogonality property of their estimators), as experienced in the Monti (1994) test, for instance.

A large number of proposals aimed at clustering and/or discriminating time series are based on spectral functions as those of Alagón (1989), Dargahi-Noubary and Laycock (1981), Kakizawa *et al.* (1998), Kazakos and Papantoni-Kazakos (1980), Shumway (1982, 2003) and Shumway and Unger (1974) and noticeable those derived by comparing periodograms and log-periodograms, as Caiado *et al.* (2006, 2009).

Further measures are derived from divergence concepts (Corduas, 1985a; Chaudury *et al.*, 1991; Gersh *et al.*, 1979; Kailath, 1967), wavelet analysis (Struzik and Siebes, 1999) and forecast densities (Alonso *et al.*, 2006).

We linger over a few proposals related to the AR metric and generated by the definition of *cepstrum* introduced by Bogert *et al.* (1962). The cepstrum coefficients  $c_j$  are obtained by the parametric expansion of the logarithm of the spectrum  $f_Z(\omega)$  of a stationary process  $Z_t$ , so that:

$$c_j = \frac{1}{2\pi} \int_{-\pi}^{\pi} \log[f(\omega)] e^{-i\omega j} d\omega, \quad j = 1, 2, \dots$$

and  $c_0 = \log(\sigma^2/(2\pi))$  by Kolmogorov identity. Gray and Markel (1976) proposed the Euclidean distance  $\delta(X_t, Y_t)$  among the cepstral coefficients of two stationary processes  $X_t$  and  $Y_t$  as an effective metric among time series data. The proposed metric correctly excludes the  $c_0$  coefficient arguing that it is a scale factor. It has been applied with some interesting results by Kang *et al.* (1995), Kalpakis *et al.* (2001), Savvides *et al.* (2008); see also: Childers *et al.* (1975), Boets *et al.* (2005). A weighted version of  $\delta(X_t, Y_t)$  has been reformulated by Martin (2000) who completely ignores the existence of any other metric. Recently, Maharaj and D'Urso (2011) argument in favour of fuzzy methods involving cepstral coefficients as a basic metric for their proposal of time series clustering.

Indeed, cepstral coefficients have several properties, including relationships with spectral exponential models of Bloomfield (1973) and with the partial auto-

correlation function (Li, 2004). It is worth to observe that, with obvious notations, the following identity holds:

$$\int_{-\pi}^{\pi} |\log[f_X(\omega)] - \log[f_Y(\omega)]|^2 = \sum_{j=-\infty}^{\infty} (c_{Xj} - c_{Yj})^2 = 2\delta^2(X_t, Y_t) + \log\left(\frac{\sigma_{aX}^2}{\sigma_{aY}^2}\right).$$

As a consequence, if the processes have different degree of non-stationarity the cepstral metric is not defined. A further problem is generated by the fact that, after few lags, the cepstral coefficients are nearly zero. This circumstance may support their computational convenience but shows that any cepstral metric is heavily determined by few AR parameters.

Finally, it is important to quote the pioneering work of Zani (1983) and the results of some Italian researchers whose contributions are relevant in this area and are consistent with our perspective. Specifically, Baragona (2001) and Baragona *et al.* (2001) introduced genetic algorithms to measure diversity in time series data. Moreover, Ingrassia *et al.* (2003) applied functional analysis and Cerioli *et al.* (2004) performed clustering by means of symbolic analysis.

## 8. CONCLUDING REMARKS

Time and/or spectral properties are the stylized features of any time series generated by ARIMA models: these characteristics are fully conveyed by the forecast function. Economists use exactly the same logic leading to AR metric when they introduce the concepts of *parallelism between time series*, as shown by Triacca (2004b) or pairwise and multiple *similarity of dynamics of phenomena* introduced by Bernard and Durlauf (1996), as discussed by Palomba *et al.* (2008).

Thus, the AR formulation is a fundamental issue for econometric and time series analysis, both for stationary and non-stationary processes. Notice that non-linearity and deterministic trends are excluded from our approach; thus, when these dynamics are relevant, we suggest to move towards non-parametric metrics, as for instance those discussed by Zhang and Taniguchi (1995).

A further issue to be analyzed concerns the peculiar specificity of the AR metric to discriminate among dynamic strictures and not among observed data, as emphasized by Cubadda (2007, personal communication). If two processes  $X_t$  and  $Y_t$  are defined by different ARMA operators applied to the same WN  $a_t$  their time realizations are obviously deterministically related (a perfect forecast of  $Y_t$  is possible from the knowledge of  $X_t$ ) but their AR distance is positive. On the contrary, we may obtain a null AR distance between processes with the same ARMA operators even if different WN processes may generate quite different realizations and dynamic patterns.

Since any distance measure both enhances and hides several aspects of the compared objects, it is important to recognize that the AR metric is a distance among rational operators irrespective of time series realizations. Then, the AR



*metric* is a useful tool for several statistical objectives if the whole *structural diversity* is the main point of the analysis. On the other hand, a *spectral metric* could be more effective if the comparison involves *local features* (e.g. long memory, periodic patterns, seasonality, etc.).

As a matter of fact, in the AR metric, the contribution of each  $\pi_j$  coefficient to the stochastic components of the process is spread over all the angular frequencies; thus, this metric should not be applied if our concept of closeness is related to some specific frequential component. For instance, Caiado *et al.* (2006) proved by simulation that a periodogram-based measure may result more effective than the AR metric for detecting a non-stationary behaviour. Similarly, Piccolo and Corduas (2006) supported a spectral metric when the angular frequencies around origin are the central issue for assessing the similarity among stationary and fractional difference processes.

As a conclusion, we emphasize that the AR metric is well defined for stationary and non stationary, short and long memory, seasonal and non seasonal stochastic processes; it encompasses the relevant time and frequential domain features of a time series dynamics in a parsimonious parametric way. Thus, according to our opinion and experiences, the AR metric is a powerful and wide applicable tool to study and understand the relationships among time series, but it also helps to produce new ideas, genuine proposals and innovative developments.

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#### SUMMARY

##### *The Autoregressive metric for comparing time series models*

The Autoregressive metric was firstly introduced in 1983 as a tool for choosing a representative element from a large collection of time series and for clustering temporal data. The proposal has been extended to many contexts and has raised increasing interests in both time series methods and applications. The main results concerning this metric, its asymptotic distribution and some operational and comparative issues are presented. A discussion about the merits of this distance criterion and some caveats about its usage conclude the paper.